

GOES SATELLITE TIME CODE DISSEMINATION

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ABSTRACT

The National Bureau of Standards, in cooperation with the National Oceanic and Atmospheric Administration (NOAA), has been disseminating a time code referenced to UTC(NBS) via two of NOAA's geostationary GOES satellites since 1975. A review of the GOES time code system, the performance achieved to date, and some potential improvements in the future will be discussed.

The disseminated time code is originated from a triply redundant set of atomic standards, time code generators and related equipment maintained by NBS at NOAA's Wallops Island, VA satellite control facility. It is relayed by two GOES satellites located at 75°W and 135°W longitude on a continuous basis to users within North and South America (with overlapping coverage) and well out into the Atlantic and Pacific ocean areas. Downlink frequencies are near 468 MHz. The signals from both satellites are monitored and controlled from the NBS labs at Boulder, CO with additional monitoring input from geographically separated receivers in Washington, DC and Hawaii. Received time code accuracies are typically better than 1 ms if the user only applies a constant correction to compensate approximately for his geographical location or better than 100 μ s if manual or automatic corrections are applied for path delay using satellite position data encoded into the GOES time code signals.

Performance experience with the received time codes for periods ranging from several years to one day is discussed. Results are also presented for simultaneous, common-view reception by co-located receivers and by receivers separated by several thousand kilometers.

Based on the general acceptance of the GOES time code, NBS and NOAA have recently extended their formal Memorandum-of-Agreement to continue the GOES time code operations for at least an additional five-year period.

INTRODUCTION

In 1975 the National Bureau of Standards (NBS) began regular dissemination

Report Documentation Page				Form Approved OMB No. 0704-0188	
Public reporting burden for the collection of information is estimated to average 1 hour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing the collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing this burden, to Washington Headquarters Services, Directorate for Information Operations and Reports, 1215 Jefferson Davis Highway, Suite 1204, Arlington VA 22202-4302. Respondents should be aware that notwithstanding any other provision of law, no person shall be subject to a penalty for failing to comply with a collection of information if it does not display a currently valid OMB control number.					
1. REPORT DATE DEC 1982		2. REPORT TYPE		3. DATES COVERED 00-00-1982 to 00-00-1982	
4. TITLE AND SUBTITLE Goes Satellite Time Code Dissemination				5a. CONTRACT NUMBER	
				5b. GRANT NUMBER	
				5c. PROGRAM ELEMENT NUMBER	
6. AUTHOR(S)				5d. PROJECT NUMBER	
				5e. TASK NUMBER	
				5f. WORK UNIT NUMBER	
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) National Bureau of Standards, Time and Frequency Division, Boulder, CO, 80303				8. PERFORMING ORGANIZATION REPORT NUMBER	
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES)				10. SPONSOR/MONITOR'S ACRONYM(S)	
				11. SPONSOR/MONITOR'S REPORT NUMBER(S)	
12. DISTRIBUTION/AVAILABILITY STATEMENT Approved for public release; distribution unlimited					
13. SUPPLEMENTARY NOTES Proceedings of the Fourteenth Annual Precise Time and Time Interval (PTTI) Applications and Planning Meeting, Greenbelt, MD, 30 Nov - 2 Dec 1982					
14. ABSTRACT see report					
15. SUBJECT TERMS					
16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT Same as Report (SAR)	18. NUMBER OF PAGES 24	19a. NAME OF RESPONSIBLE PERSON
a. REPORT unclassified	b. ABSTRACT unclassified	c. THIS PAGE unclassified			

of an NBS-referenced time code via two geostationary GOES satellites (Geostationary Operational Environmental Satellites) operated by NOAA (National Oceanic and Atmospheric Administration). The primary mission of the GOES satellites and associated support systems is to gather a variety of environmental data from various sources, including large numbers of remotely located sensing platforms throughout the Western hemisphere, relay the information via the satellites to a central processing facility, and make the processed information available to the World Meteorological Organization and other interested users. The NBS time code is interleaved into the data collection platform interrogation channel, providing a continuously available accurate time-of-day reference both for internal NOAA data handling operations and for more general time and frequency applications throughout much of the Western hemisphere. Commercial time code receivers are readily available for a few thousand dollars that can provide received timing accuracies of better than 100 μ s over averaging periods of hours, months, or years.

The cooperative NBS/NOAA program to provide and disseminate the NBS time code via the operational GOES satellites was formalized for a five-year period in May, 1977 by an NBS/NOAA Memorandum-of-Agreement, which was extended by both organizations in May, 1982 for an additional five-year period. Since 1975, significant improvements have been made in the NBS time code generation and control equipment at the GOES Satellite Control Facility at Wallops Island, VA; the time code control and monitoring procedures used by NBS to assure overall system accuracy and reliability; and in the newer generations of the GOES satellites themselves. In the remainder of this paper the overall GOES time code system will be described, including some recent improvements. Performance of the system during the past four years will be discussed based on reception of the time code at NBS/Boulder, the U.S. Naval Observatory in Washington, DC, and at NBS radio station WWVH in Hawaii. Finally, some potential future improvements will be described briefly.

GOES SYSTEM DESCRIPTION

The GOES time code system consists of an NBS-owned time code generation, monitoring, and control system at NOAA's Wallops Island site; the satellite uplink facilities at Wallops Island; the East and West operational GOES satellites located at 75°W and 135°W longitude, respectively; monitoring, computing, and data storage facilities at NBS/Boulder; a two-way dial-up data communication link between Boulder and Wallops Island; and support operations such as NOAA's satellite tracking operations. The triply-redundant time-code-generation system is based on three atomic standards, presently consisting of two cesium standards and one rubidium device. The time code used is specially designed for compatibility with the GOES Data Collection System and has been described in previous publications.⁽¹⁾ The code as transmitted via the two GOES satellites includes complete time-of-year information; DUT1 values -- i.e., estimates of the current difference between the UT1 and UTC time scales; and satellite position information for computing path delays. The

NBS equipment at Wallops Island also includes capabilities for measuring and storing various time difference data, fault detection and alarm circuitry, provisions for monitoring Loran-C transmissions as an independent timing reference, memory for storing 10 days worth of position prediction data for each of the two operational satellites, and modems for use with the Boulder-Wallops Island data link.

The time code is continuously transmitted from this system to the east and west GOES satellites at S-band and is then downlinked on two slightly different frequencies near 468 MHz in one of the meteorological satellite allocated bands. This constraint to use meteorological satellite frequency allocations for the GOES/East and GOES/West downlinks may result in interference in receiving the time code transmissions in some urban areas, since these allocations are shared with the very large and very active land-mobile service. Furthermore, the land-mobile use is designated as the "primary" one within the U.S. while the meteorological satellite use is "secondary." In practical terms this means that if interference to the time code is experienced from land-mobile transmissions, it must be tolerated. Fortunately, time code receivers can be designed to effectively ignore much of this type of interference when necessary. In general, the time code as received from GOES/East is less affected by interference than that from GOES/West because one of the land-mobile channels exactly coincides with the GOES/West frequency while the closest one to the GOES/ East frequency is somewhat offset.

The satellite position information included in the time code format is generated from a sophisticated, very large orbit prediction program run on a large computer at NBS/Boulder. Data inputs for this program include the satellite orbital elements which are determined from satellite tracking data obtained by NOAA and/or NASA. The computer program generates position predictions for each satellite for each hour during the next ten-day period and these are further processed by the microprocessor-based time code generation equipment at Wallops Island to generate updated values each four minutes that are then encoded along with the time information. Users then have the option to simply decode the received time information achieving accuracies of about 1 ms or to also use the position data to compute a path delay from Wallops Island to the user's particular location that is updated each four minutes to compensate for movements of the satellites. In the latter case, timing accuracies of better than 100 μ s can be achieved. GOES timing accuracy as transmitted from Wallops Island is maintained to within at least 10 μ s by continuous monitoring relative to Loran-C and by occasional portable clock trips.

Reception of the GOES time code is possible on a continuous basis throughout much of the Western hemisphere as shown by the coverage maps for both satellites in Figure 1. Overlapping coverage is provided within the continental U.S. and certain other areas. While there are also operational satellites in the European (METEOSAT) and Japanese (GMS) regions that are part of the same worldwide meteorological satellite system as GOES, these satellites do not currently include an identical or similar time code in their broadcast formats. Several forms of commercial GOES

time code receivers are currently available which feature automatic operation with small antennas. Prices range from about \$2800 to \$4000, depending on the accuracy level provided.

As the GOES time code system and operational procedures have evolved during the past few years, several improvements have been incorporated. A second-generation system has been installed at Wallops Island that provides increased reliability through triple redundancy, more elaborate diagnostic information available remotely to NBS/Boulder personnel, and the replacement of two rubidium standards with more stable (in long term) cesium devices. The information transmitted to users has been expanded to include higher-resolution satellite position data and UT1 time scale information. Monitoring has also been expanded by placing receivers at the U.S. Naval Observatory in Washington, DC and at radio station WWVH in Hawaii to provide better geographical coverage and by acquiring dedicated backup receivers for the NBS/Boulder system. GOES status information is now available to interested users via the monthly NBS Time and Frequency Bulletin⁽²⁾ and, on a more current basis, from the USNO Automated Data Service. The USNO system can be accessed using a variety of terminals at either 300 or 1200 baud with even parity. Telephone access numbers are: (202) 653-1079 (commercial); 653-1079 (FTS); and 294-1079 (Autovon). After responding to the prompt asking for identification, the GOES status information is obtained by requesting the file "NBSGO" with the command "@NBSGO" followed by a carriage return. These status reports are designed to report interruptions in service, temporary perturbations in operations which result in reduced reception accuracies or other problems, and accomplished or projected changes that affect the GOES time code. Possible additional future improvements are discussed at the end of this paper.

OBSERVED TIME CODE PERFORMANCE

In general there are three different modes in which the GOES time code can be used:

- 1) Uncorrected. In this mode the received time signal is simply decoded and used without using the position information in the signal to compute and compensate for path delays as they change due to satellite motion. The transmitted time code is advanced by a fixed 260,000 μ s. The received signals nevertheless arrive at any point within the coverage area within ± 16 ms of UTC(NBS). Furthermore, a fixed-location user can compensate for most of this fixed bias by applying a fixed correction which depends on his specific location to all received data. If this procedure is followed, the received time signal will provide an accurate local UTC reference that varies less than 1 ms in long term due to uncompensated satellite motion. In the discussions of time code performance that follow, the term "uncorrected" will refer to this mode of reception;

- 2) Corrected. In this mode either the user or the automatic receiver uses the satellite position data in the received timing signal and the known geographical locations of his site and the Wallops Island origination point to compute a specific path delay that can be updated each four minutes as the satellite position varies. When these corrections are applied to the received time code, either manually or automatically, a local version of UTC(NBS) is provided, generally accurate to within ± 100 μ s. This received accuracy at the user's site is deteriorated relative to the "as-transmitted" accuracy of about 10 μ s because the satellite position predictions used to compute path delays contain some uncertainties. Also, uncertainties and instabilities in the receiver delays can contribute to the usable accuracy as received. In the following discussions of received data this mode will be referred to as "corrected"; and
- 3) Common-view. In this mode multiple users at separated sites within the coverage area of the same satellite can compare their local clocks with one another by making simultaneous measurements of the received time code at each site. Simple subtraction of the results between two sites yields clock differences that to some degree are insensitive to the actual satellite position and any time errors that may exist between UTC and the transmitted code. In this case the received timing signal functions only as a "transfer standard" to compare two or more clocks.

Observed Performance in "Uncorrected" Mode

Figures 2-5 show some of the results of monitoring the uncorrected GOES/East and GOES/West time codes at NBS/Boulder. In all cases the Y-axis is (UTC(NBS) - the received time code) in microseconds with no correction being applied for Boulder's fixed location. Figures 2 and 3 show typical results (for GOES/East and GOES/West, respectively) over a period of several weeks where each plotted point is an hourly measurement of (UTC(NBS) - received signal). The obvious variations within each day are due to satellite motion which varies the path delay. For GOES/East during this period the maximum peak-to-peak variation was less than 200 μ s. The GOES/West hourly data in Figure 3 show somewhat larger daily variations of about 250 μ s during part of the period and a definite change on day #19 when a GOES/West satellite station-keeping maneuver was executed. Figures 3 and 4 show the longer term variations in the received "uncorrected" time codes over a period of nearly four years. In these plots the points up to 5/1/81 (day number 852) are actually single measurements made once each day, while after 5/1/81 an average of 24 hourly measurements is plotted for each day. The somewhat-more-erratic values prior to 5/1/81 are due mainly to the greater sensitivity of single measurements to temporary perturbations from such causes as land-mobile interference. The many points where abrupt changes occur, producing the "scalloped" appearance, correspond to days on which satellite station-keeping maneuvers took place. Note especially in Figure 4 how the station-keeping on GOES/East has improved since the shift to a new GOES/East satellite (GOES-5) at about day #970 on the plot. The important

point, however, is that during the entire four-year period both satellites provided a UTC time reference that varied by less than ± 1 ms with respect to a fixed offset due to Boulder's geographical location.

Observed Performance in "Corrected" Mode

Figures 6-9 show received data obtained with commercial receivers that automatically use the satellite position data to compute updated path delays and adjust the output 1pps pulse accordingly. In each plot the Y-axis runs from $-200 \mu\text{s}$ to $+200 \mu\text{s}$ with respect to UTC(NBS). Figure 6 shows the relatively short-term performance for both satellites by plotting hourly measurements over a typical 1-month period. The peak-to-peak variations within each day, ranging from about 10 to $35 \mu\text{s}$ during this period, are apparently due to small imperfections in the tracking data, orbital-element generation, or the computer program used to generate the satellite position predictions. Abrupt changes in the peak-to-peak amplitude of the daily variations are sometimes observed when a new set of orbital elements is processed (about once per week). Also, a general increase in the amplitude sometimes occurs as the time increases since the last "fresh" set of orbital elements -- e.g., note the first eight days of GOES/West data in Figure 6. Based on years of monitoring at NBS the typical peak-to-peak daily variation is about $20 \mu\text{s}$, although there have been occasional periods due to lower-quality orbital elements when values of greater than $100 \mu\text{s}$ were observed.

Figure 7 shows corresponding data over a longer period of $4\frac{1}{2}$ months where an average of 24 hourly measurements is plotted each day. The step change of about $40 \mu\text{s}$ that occurred in GOES/West early in August, 1982 has no apparent explanation. The more temporary large excursions of up to $150 \mu\text{s}$ in GOES/West that occurred during a two-week period around day #90 resulted from two consecutive sets of orbital elements that were of poor quality.

Figures 8 and 9 show the long-term performance over nearly four years of the GOES/East and GOES/West time codes, respectively, as received at NBS/Boulder. Each point prior to May 1, 1981 (day number 852) is a single measurement per day while each point after that time is a daily average of hourly measurements. Considering the entire period of more than 1400 days, the received time codes from both satellites, averaged over a day, have generally remained within $\pm 100 \mu\text{s}$ of UTC(NBS) with the exception of occasional brief periods of 1-15 days.

Based on the experience at NBS during 1982 (325 days), a GOES/East time code user would have observed daily averages within $\pm 25 \mu\text{s}$ of the mean value 95% of the time and no values greater than $50 \mu\text{s}$ from the mean. A corresponding GOES/West user, however, would have observed only about 65% of the values falling within $\pm 25 \mu\text{s}$ of the mean, although 93% of them would be within $\pm 50 \mu\text{s}$.

Observed Performance in "Common-view" Mode

Figures 10-12 summarize the relatively short-term performance over about a 1-month period when the GOES time code is used in the "common-view" mode. In Figure 10, the hourly measurements of GOES/East are plotted from two co-located receivers at NBS/Boulder along with the hourly differences in the values. Although the output of each receiver has time code variations of several tens of microseconds, the differences between the simultaneous hourly measurements remain generally stable to within a few microseconds with occasional jumps of 5-10 μ s.

Figures 11 and 12 show similar data for receivers which are separated thousands of kilometers. Figure 11 applies to the simultaneous reception of GOES/East at NBS/Boulder and the USNO in Washington, DC while Figure 12 applies to reception of GOES/West in Boulder and Hawaii. Although the Boulder/Washington differences are not much worse than for the co-located receivers, the Boulder/Hawaii differences show larger variations and a relatively large step change at about day #25 on the plot. The Boulder/Hawaii data may be adversely affected by the greater sensitivity of the GOES/West downlink frequency to land-mobile interference and by the fact that the Hawaii receiver is an older model, not containing some improvements incorporated into the later versions used in Boulder and Washington.

Figure 13 presents all of the NBS/USNO common-view data currently available, but in this case, using daily averages of the hourly measurements at each site. At present it is not clear why the results seemed to improve since early October, 1982. Finally, all the available Boulder/Hawaii common-view differences based on daily averages are shown in Figure 14. The data gap in mid 1982 results from a failure in the receiver at WWVH. The observed common-view performance with GOES/West during this period is clearly inferior to the NBS/USNO comparisons via GOES/East. Further testing will be necessary in order to identify the specific cause or causes.

Based on the available data to date it appears that the common-view approach with GOES should not be depended on for comparisons of separated clocks to better than 10 μ s. Such a result is probably not too surprising in view of the constraints imposed by the 400-Hertz bandwidth limitation on the GOES time code channel.

SOME POTENTIAL FUTURE IMPROVEMENTS

- 1) NBS Access to More Current Position Data. Under present operating procedures, there sometimes are substantial delays between the creation of a revised set of satellite orbital elements by NOAA or NASA and the time at which new position predictions based on them can be inserted into the time code transmissions. The current procedure requires distribution of the orbital elements from NOAA to NASA and then to NBS, the running of a large computer program in Boulder to generate the revised position data, and the transmittal of

these predictions to the Wallops Island equipment. The delays involved may be particularly significant at times when satellite maneuvers are implemented. Efforts are now in progress to streamline this process by developing direct access by NBS to the most current satellite data residing in NOAA's computer at Suitland, MD. It may also prove feasible to generate improved position predictions more quickly and more efficiently directly from the GOES tracking data obtained approximately every four hours for each satellite.

- 2) Accuracy Indicators in Time Code. Suggestions to include in the time code format some indicator of when the usable accuracy is degraded due to various reasons are under consideration. Unused code bits are available for this purpose and receiver manufacturers have indicated willingness to provide a corresponding visible or other form of alert at the user's receiver as appropriate.
- 3) Automatic Compensation for Eclipse Periods. Due to GOES spacecraft limitations the time code transmissions are shifted to an in-orbit spare satellite at 106°W longitude for scheduled 2-hour periods each day during eclipse periods (March 1-April 15 and Sept. 1-Oct 15). During these 2-hour periods the satellite position data cannot at present be revised to reflect the spare satellite's position. Changes to the GOES time code system software at Wallops Island are being considered to alleviate this problem.
- 4) Automatic Delay Monitoring at Wallops Island. At present equipment delays through the Wallops Island transmission channel processing equipment are not monitored directly and could introduce uncompensated changes in path delay when subsystems are replaced or modified. Capabilities for monitoring such station delays may be incorporated in the future.
- 5) Use of GOES Trilateration System for Higher Accuracy Time Transfer. Some of the current limitations in GOES timing accuracy are related to the limited 400-Hz interrogation-channel bandwidth available and uncertainties in the satellite position predictions. NBS plans to investigate the possibility of removing or reducing these limitations through the use of the GOES trilateration ranging system for time transfer. Ranging signals are transmitted at about 1.6 GHz approximately every four hours. With sidetones as high as 200 kHz, these ranging signals could provide timing resolution in the 1 ns range. Furthermore, since the satellite positions are determined accurately during each of the ranging operations, time transfers should be possible at these times with both higher precision and higher accuracy. Benefits may be realizable in both a general dissemination mode and a higher accuracy common-view comparison mode.

ACKNOWLEDGEMENT

NBS would like to acknowledge the assistance of Arbiter Systems, Inc. and

the U. S. Naval Observatory in making possible the additional GOES/East monitoring capability in Washington, DC and also USNO's provision of its Automated Data Service facilities for the GOES status reports.

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- (2) NBS Time and Frequency Bulletin. Available upon request to Time and Frequency Division, National Bureau of Standards, 325 Broadway, Boulder, CO 80303.

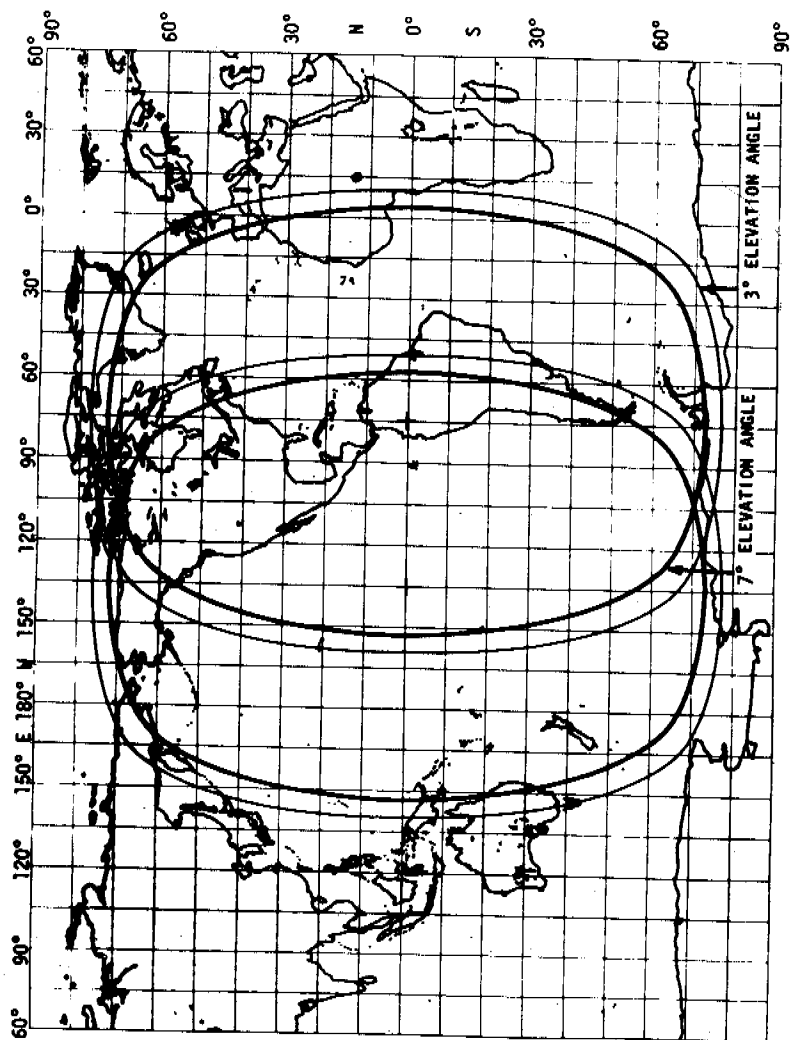


Figure 1. GOES-East and GOES-West coverage areas.

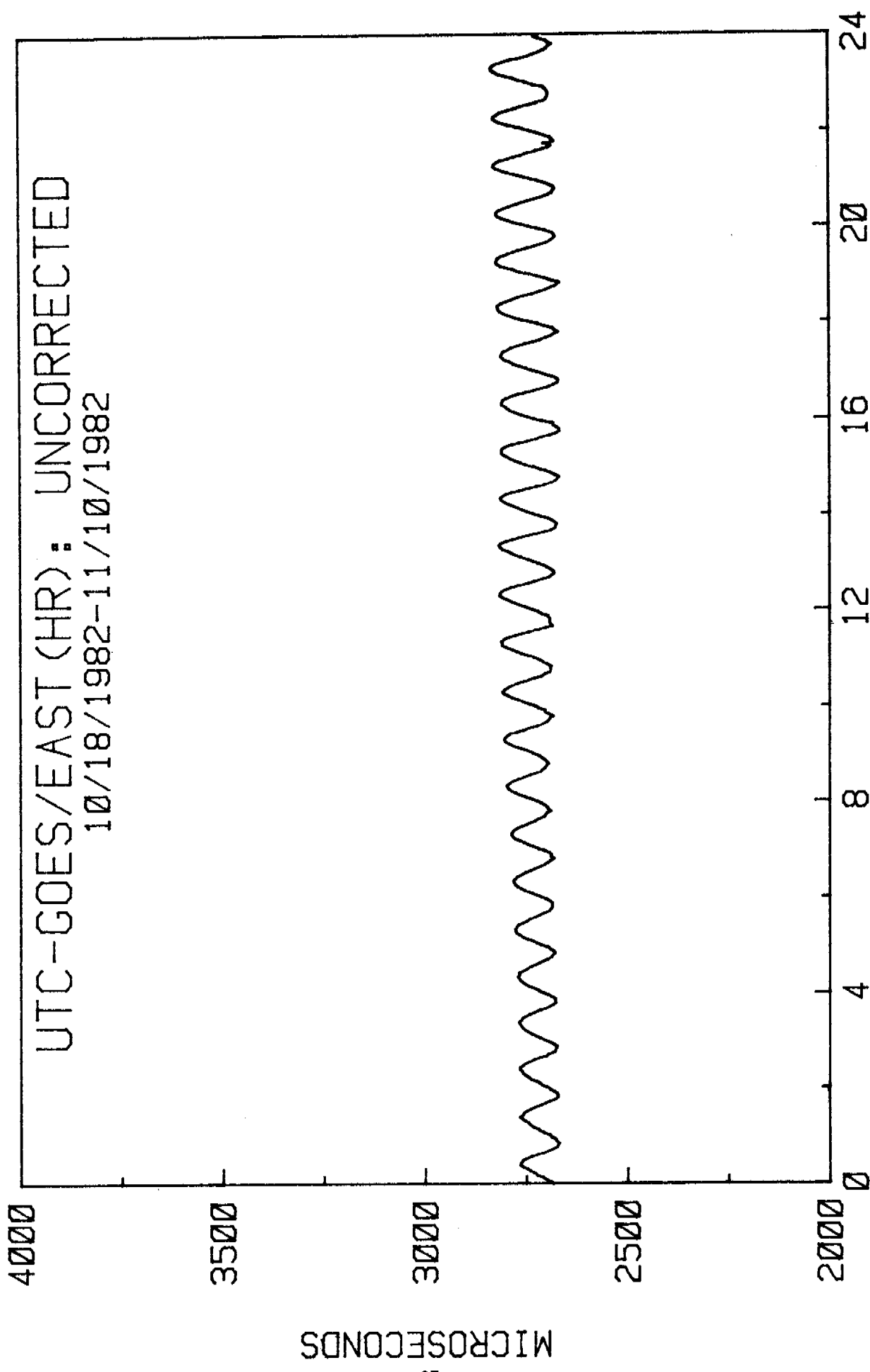


Figure 2

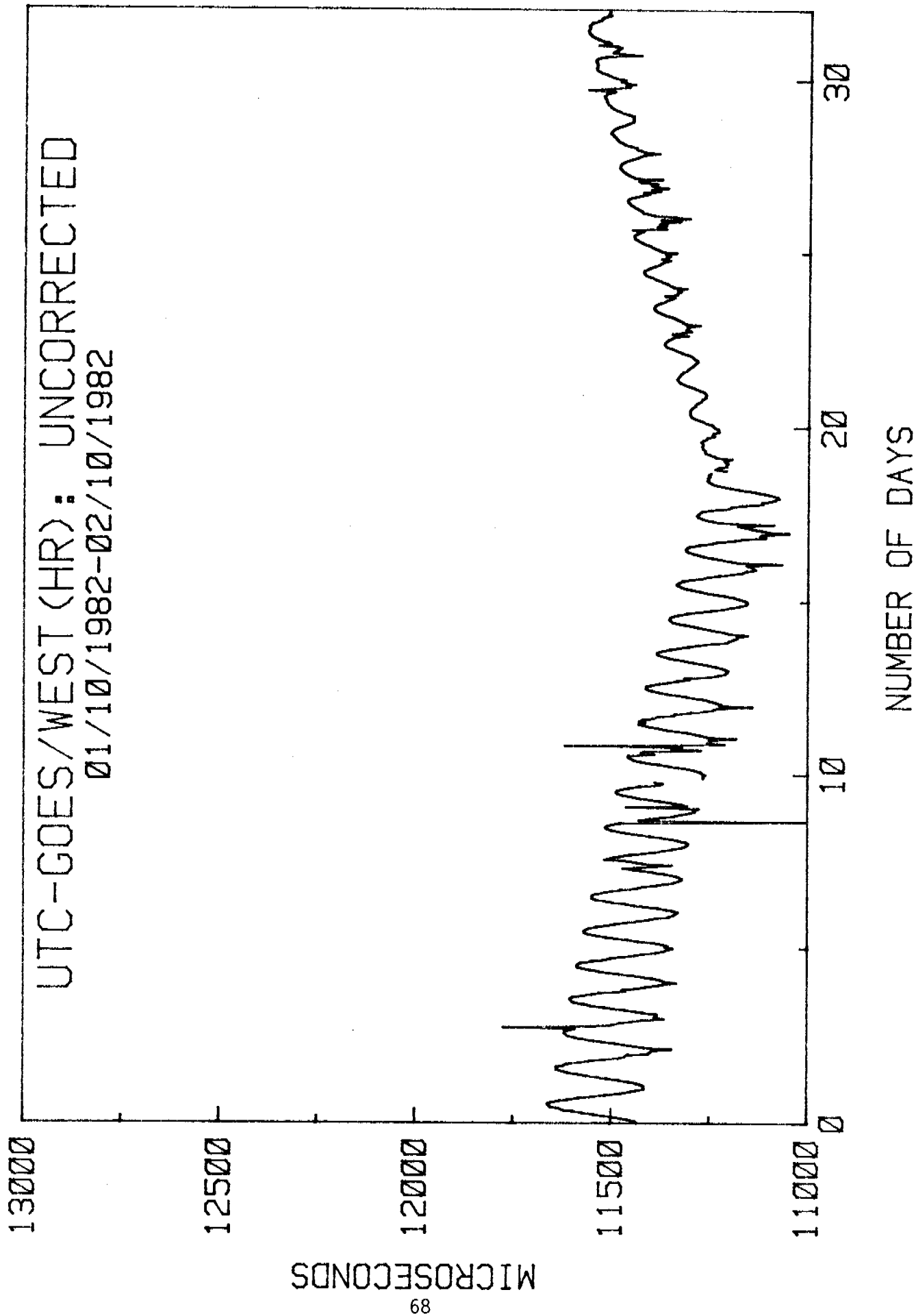
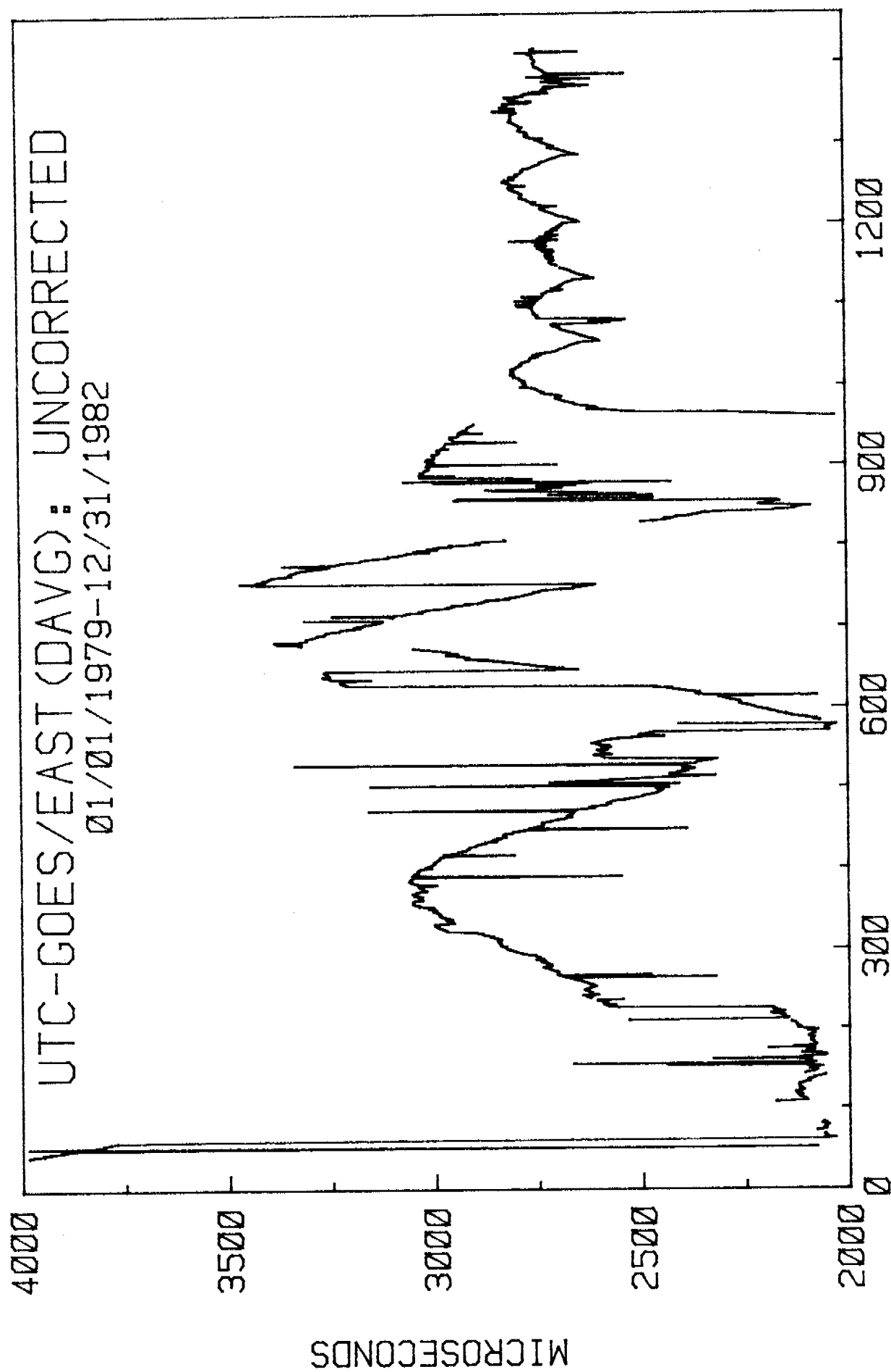
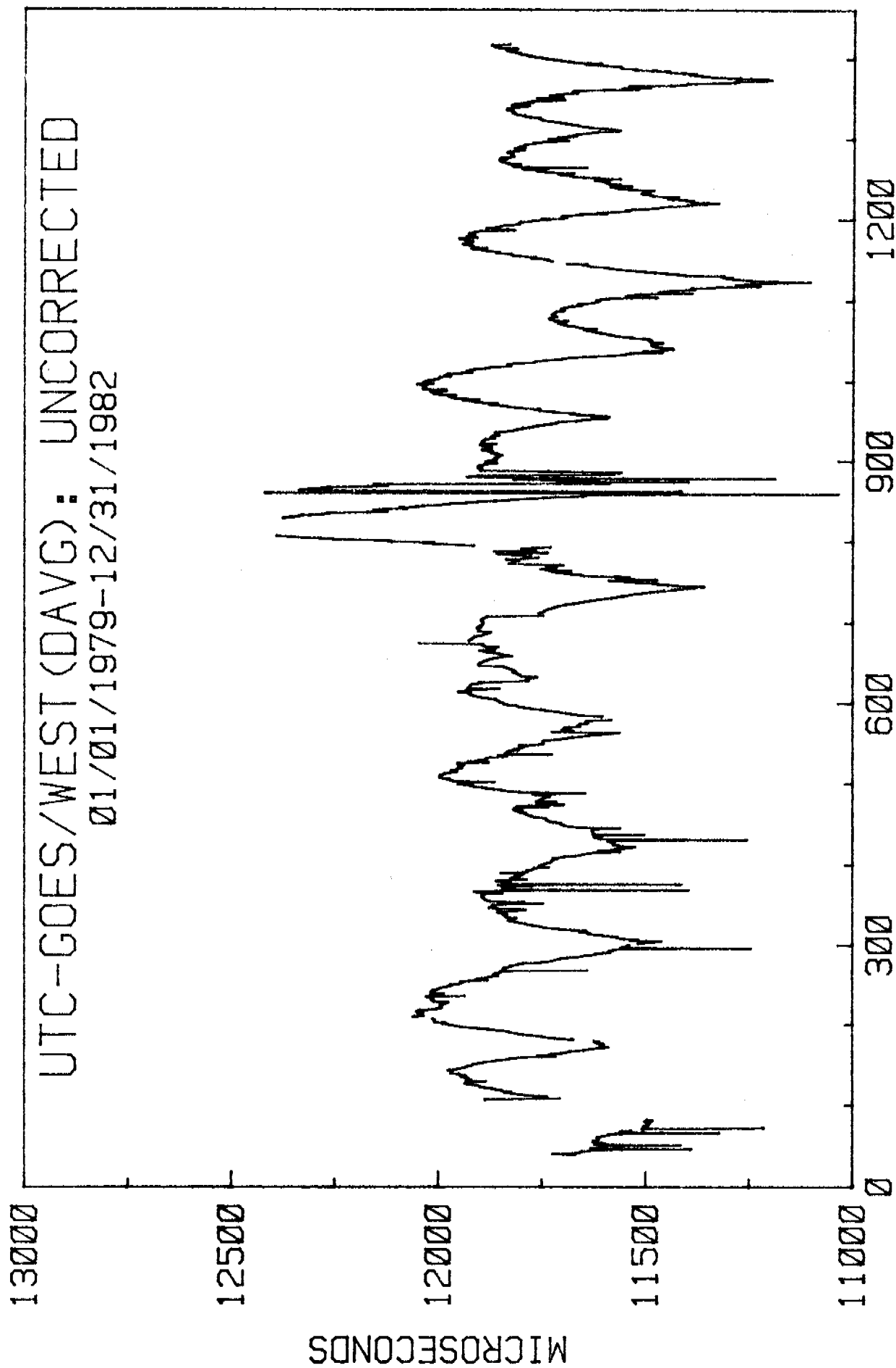


Figure 3



NUMBER OF DAYS

Figure 4



NUMBER OF DAYS

Figure 5

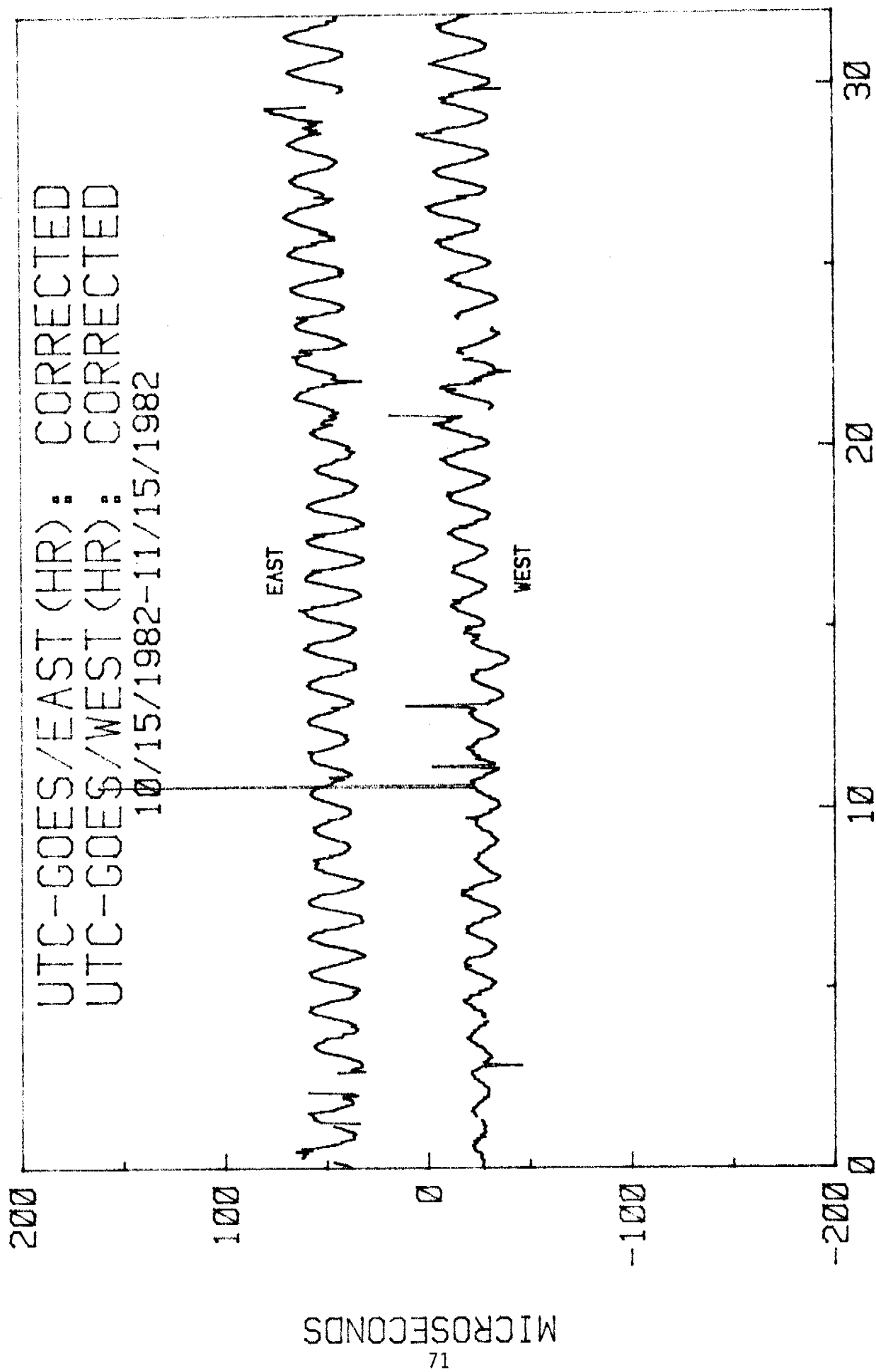


Figure 6

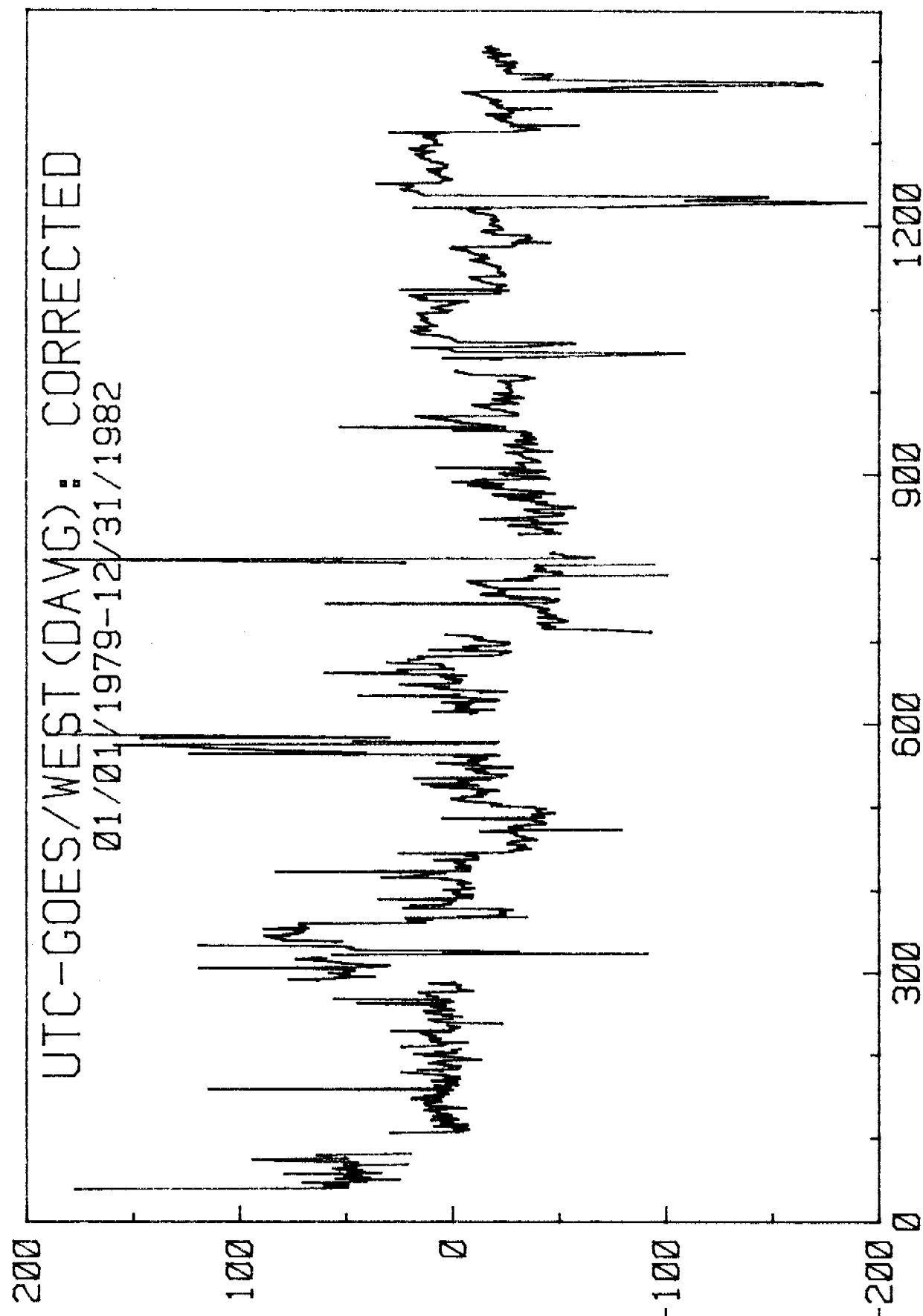


Figure 9

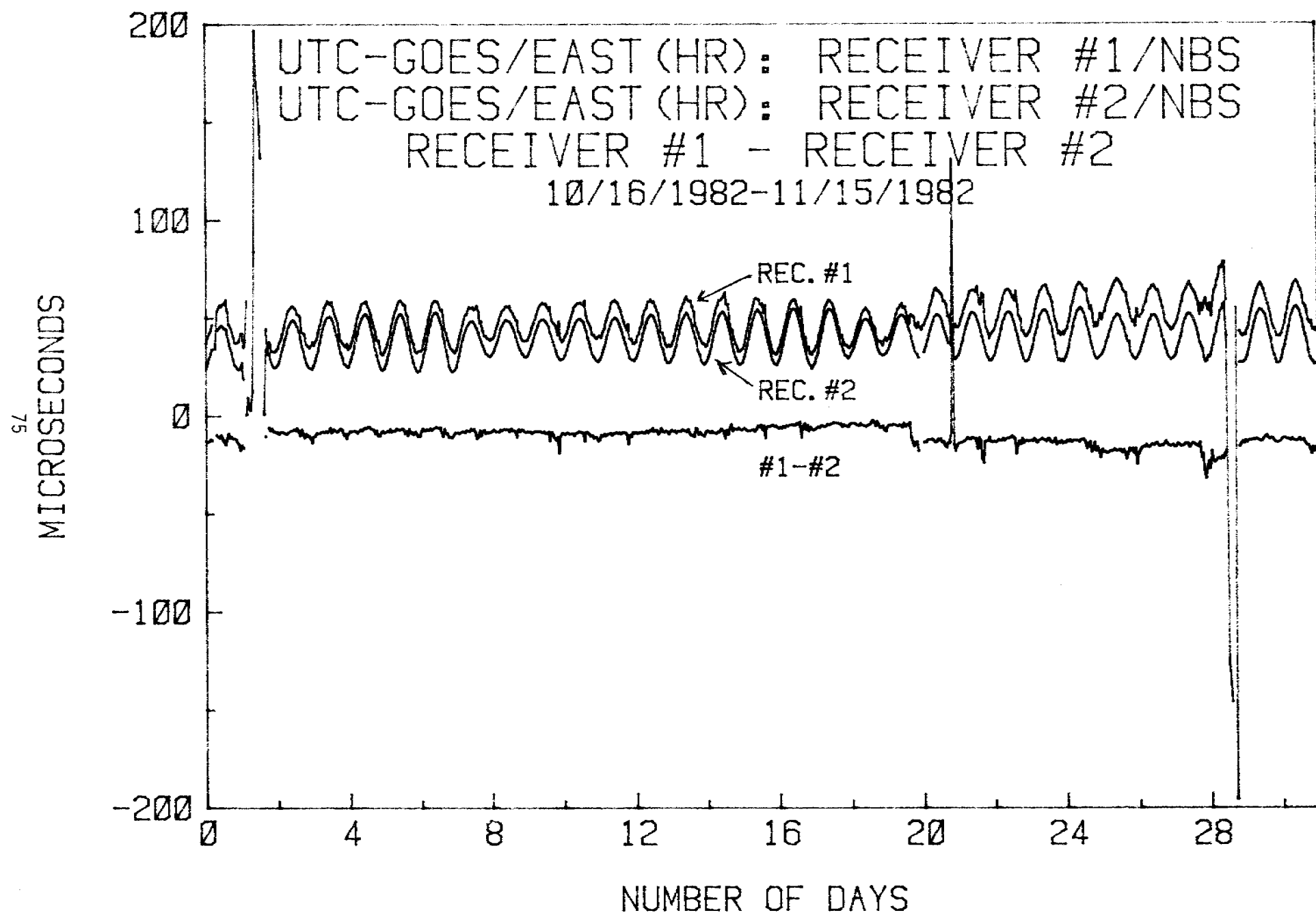


Figure 10

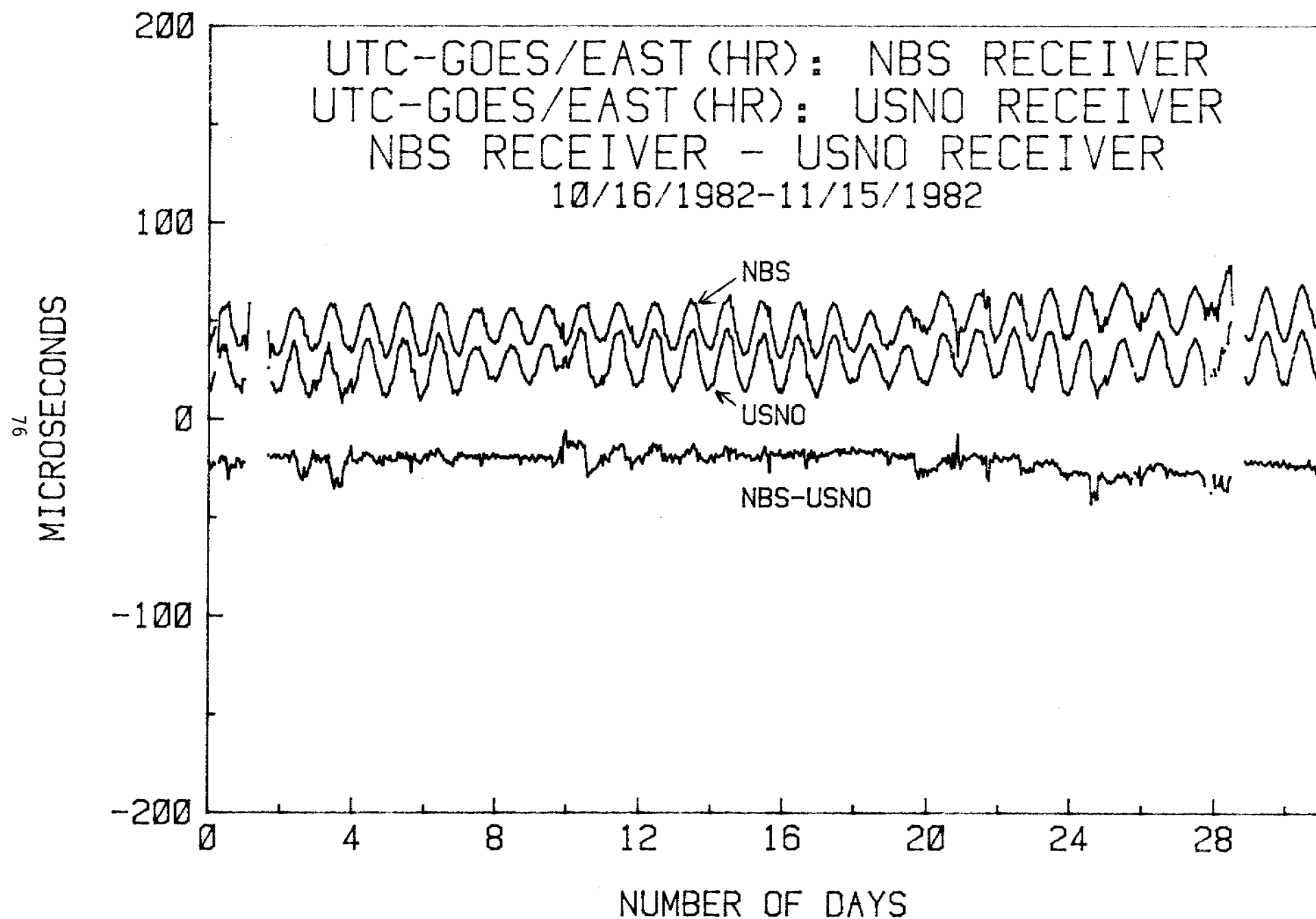


Figure 11

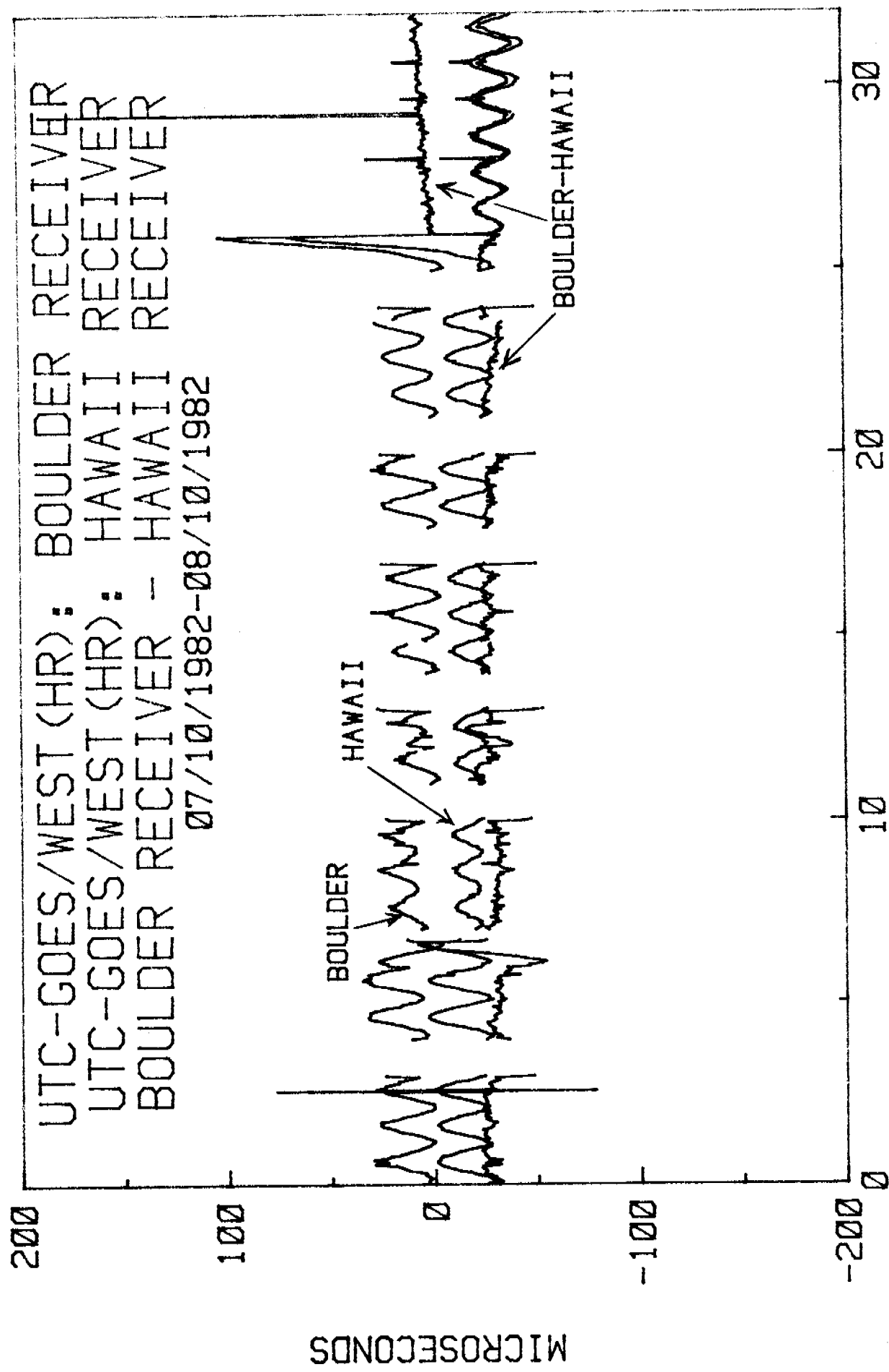
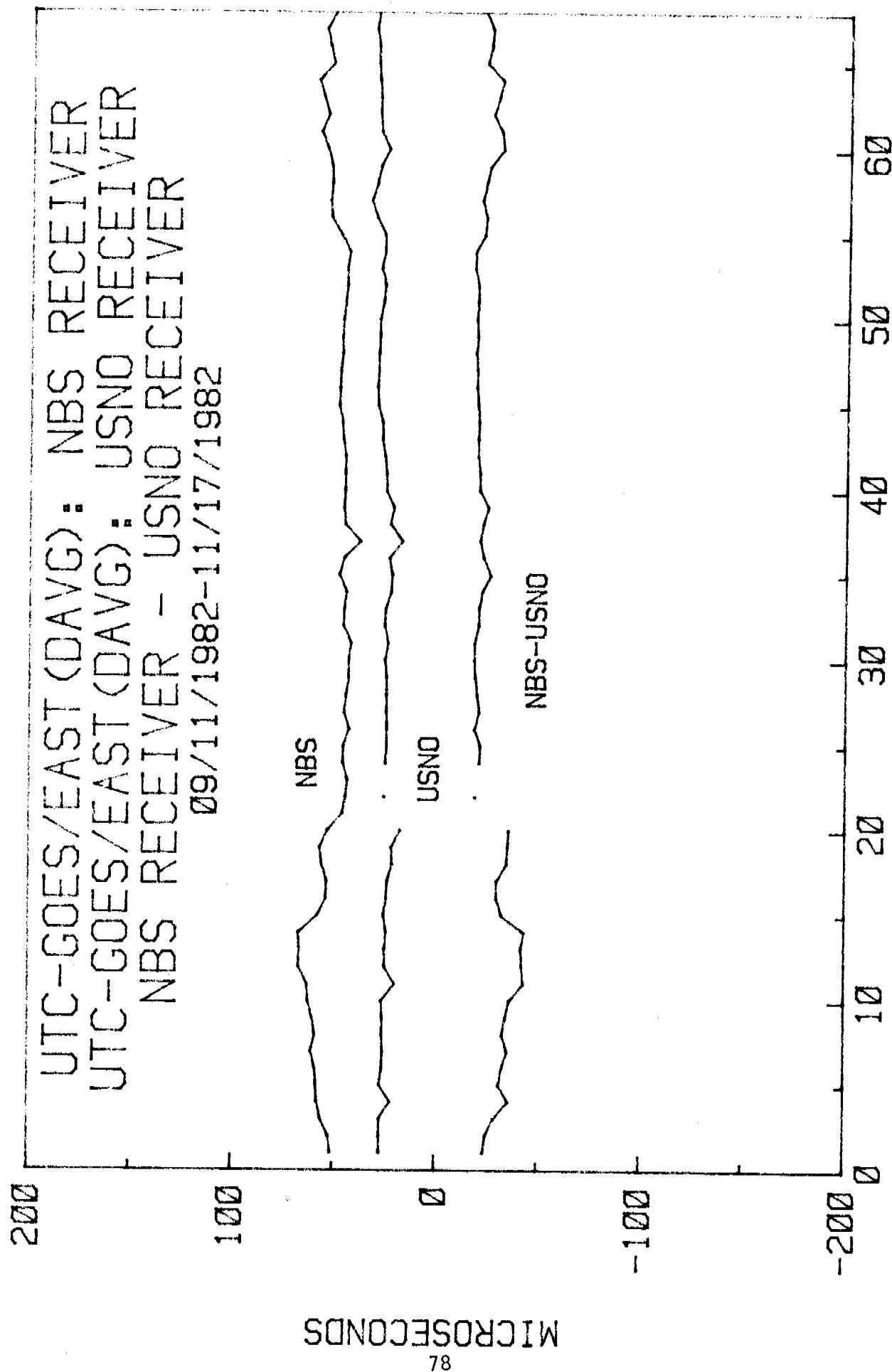


Figure 12



NUMBER OF DAYS

Figure 13

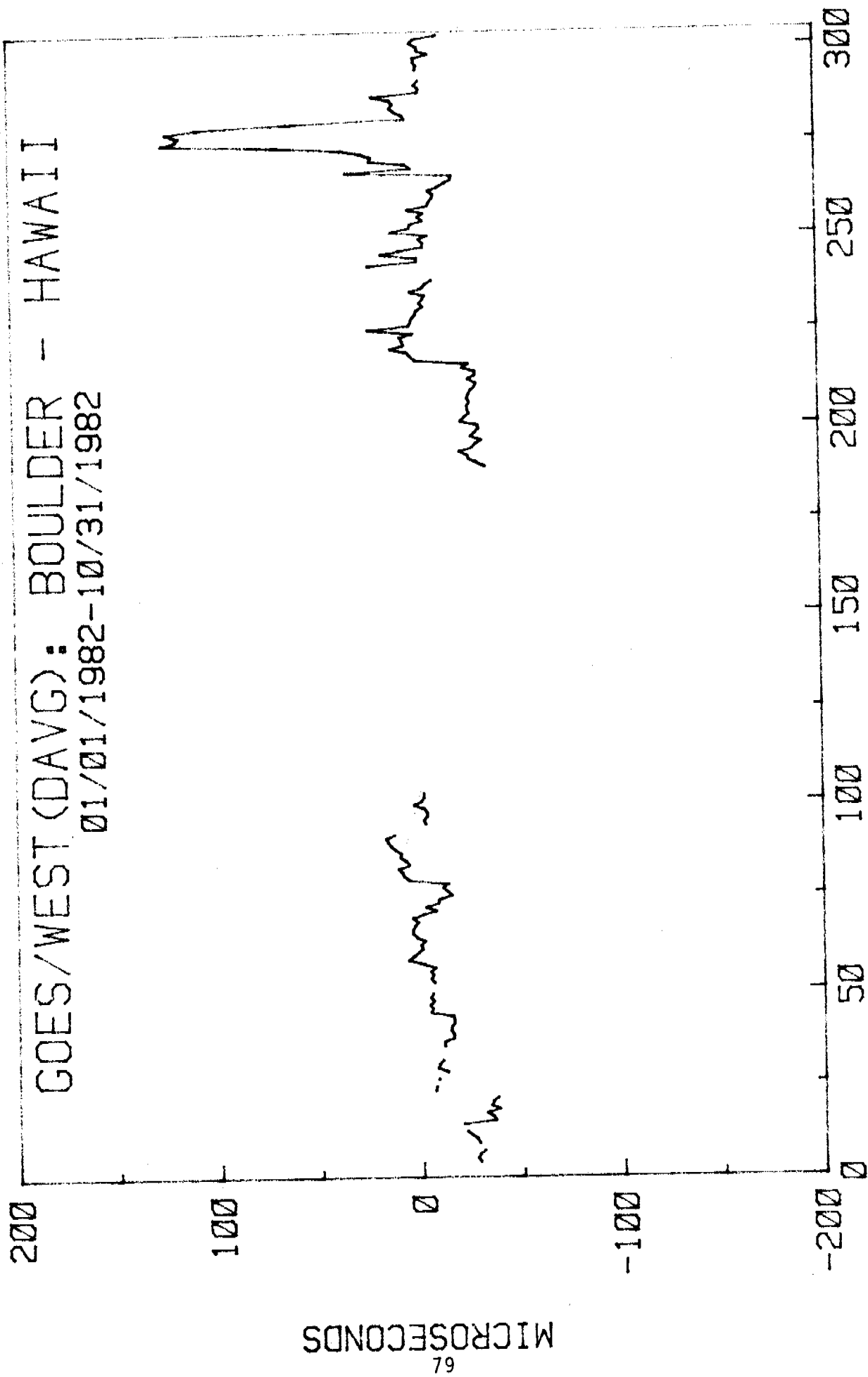


Figure 14

QUESTIONS AND ANSWERS

MR. ANDREW C. JOHNSON, USNO

Is there any possibility of expanding an area of coverage to other governments?

MR. BEEHLER:

The U.S. GOES satellites are part of an international system which include the MEDISAT Satellites in the European area and GMS Satellites in the Japanese area. There have been some continuing discussions relative to providing the code that we provide here, or something similar on those satellites to make it into pretty much an international system.

At present, I understand that the decision of the Japanese government is not to include the time code and the European Space Agency still has under consideration, including it on the European System. But, at present there are no definite plans.

AUDIENCE:

I have a question concerning your Wallops Island set-up, the 3 cesium standards, are they configured as an ensemble or a simple redundancy?

MR. BEEHLER:

They're configured now just for simple redundancy.

DR. KELLOGG:

Last year, Allan talked to us a little bit about another development in Boulder using the GPS Satellite between Boulder and the US Naval Observatory. In the longer range future, will both of these co-exist or will you choose the better of the two or if not?

MR. BEEHLER:

Well, I think for the foreseeable future we would say that they're both going to co-exist. I think you want to keep in mind, first of all, that we're really dealing with different accuracy capabilities here. At least with the time code constraints as we reported here today, your really confined to something at the 50 to 100 microsecond level, with GPS on the other hand the measurements have shown that you're able to do better than 100 nanoseconds. So they are not really competing systems.

I think, especially at the moment and if the tri-lateration were on the GOES system, would eventually look favorable at the one to ten nanosecond range, then I think one just simply has to look at probability of the GPS signals continuing to be available and the trade-off involved, the cost and so on before making any long-term decision.

DR. KELLOGG:

That raises another question, may I please? Do you have an idea of the relative size of the two bodies of customers for the different precision signals?

MR. BEEHLER:

Well, I think there's no question that the larger number of users of course are for the more modest accuracy needs. If you look at, for example, the users of WWV, they probably number in the hundreds of thousands.

When you get down to the GOES region where you're talking about perhaps fifty to 100 microseconds the users of that service are probably numbering between 500 and a 1,000 at the present time.

When you get down to the GPS capabilities of better than 100 nanoseconds I really can't answer except I'm sure it's a much smaller number.

DR. WINKLER:

That is true, I'd like to share also here in this discussion what we have observed, however, that a system when it becomes very reliable then the greatest capability system will carry the day.

In other words, people will buy receivers for the one system which can satisfy all requirements. That brings me, of course, back to a question which we just had before, a comparison between the different systems, essentially has to be made, I believe on the basis of one-way versus two-way operation. In the case of the two-way operation, the system determines the propagation delay for you, or by transmission and reception, the propagation problem simply goes away. And, therefore, a two-way system, at the expense of transmitting at the site, which may not always be possible or practical, but it does provide for essentially a much less expensive capability down to the nanosecond region.

In favor of the one-way system, one can only repeat that it doesn't require transmissions; it can be set up anywhere on earth; but, because you have to compute the propagation delays very carefully it is essentially a more expensive solution.

I can see the future, both of them co-exists. Where the one-way systems will, eventually be the counsel of despair for all the users who cannot transmit and I think that they are the large majority of the users. Where as the two-way comparisons will be used mainly by those who have an easy access or are nearby a communication terminal or communications center where the transmission problem really does not exist.

I think you will see in the future, both of these methods to co-exist and a question whether those can be pushed to that kind of a precision or not, will have to be seen.

DR. KELLOGG:

You added UT-1, to the capability to the signal, was this as an experiment or as a responsive to a demand?

MR. BEEHLER:

Well, I'd say it's in response to a small demand. The particular user that was interested in this is involved with electric power system timing. And, the reason for needing it, it's kind of a strange application you might think, but the reason goes back to historical arguments. They simply have a large number of older receivers in the system, which at one point in time were configured in a hardware sense to use UT-1, and if they cannot continue to reference to UT-1 and they switched to UTC as a reference then they would have to modify in a hardware sense many of the older equipment. So they would prefer to let that go until the equipment just naturally phases out.

DR. WINKLER:

One more point, by using UT-1 you don't have the leap seconds.